A Piezoelectric-Resonator-Based DC-DC Converter Demonstrating 1 kW/cm³ Resonator Power Density

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Abstract—Piezoelectric components hold promise for power conversion with unprecedented levels of power handling density at small size scales. Dc-dc converter topologies and operating modes have recently been established for high-efficiency utilization of piezoelectrics, and piezoelectric material selection and component design strategies have likewise been identified for high performance in power conversion. In this letter, we apply these developments to experimentally demonstrate the extraordinary power density capability of piezoelectrics. This 275-150 V, 12 W prototype achieves a piezoelectric resonator power handling density of 1.01 kW/cm³ at 493 kHz, greatly exceeding the densities of previous designs and validating the significant miniaturization potential of piezoelectrics for power conversion.

Index Terms-piezoelectric resonators, dc-dc power conversion

I. INTRODUCTION

Passive components, particularly magnetics (i.e., inductors and transformers), have long impeded the miniaturization of power electronics. Magnetics have fundamentally decreasing power densities and efficiencies at low volume [1], [2] but provide critical functionality for achieving efficient voltage regulation. Piezoelectric components, which store energy in the mechanical compliance and inertia of a piezoelectric material, have emerged as promising alternatives to magnetics for power conversion at small size scales [3], [4]. Piezoelectrics offer numerous advantages including high quality factors, high energy densities, galvanic isolation (with multi-port components), planar form factors, batch fabrication, and potential for integration.

Magnetic-less dc-dc converters based on piezoelectric resonators (PRs) have been demonstrated with high efficiency in [5]–[10]. These designs are based on recently-developed switching sequences and associated circuit topologies that maximize the PR's utilization across wide operating ranges; several of these are enumerated in [5]. Likewise, design tools including figures of merit for piezoelectric materials and vibration modes as well as guidelines for optimizing PR geometry for power conversion have been proposed in [11]. The framework of [11] reveals that – unlike magnetics – the power handling densities of PRs fundamentally increase at small scales.

In this letter, we combine these recent developments in topologies, switching sequences, material selection, and PR design criteria to experimentally demonstrate the power density promise of piezoelectrics. To the authors' knowledge, the resulting prototype achieves the highest PR power handling density of any PR-based dc-dc converter reported to date, and demonstrates the value of the aforementioned developments in enabling high power density.

II. DESIGN PRINCIPLES

To demonstrate the exceptional power density capability of piezoelectrics, we design a prototype converter with the objective of maximizing the PR's volumetric power handling density. This is achieved by combining (a) a maximumefficiency circuit topology and switching sequence proposed in [5], with (b) a maximum-power-density PR design based on criteria for piezoelectric materials, vibration modes, and geometric dimensions developed in [11].

A. Topology and Switching Sequence

Operating modes for PR-based dc-dc converters may be conceptualized in terms of switching sequences, or specific orderings of energy transfer stages and resonant stages throughout a switching period. Switching sequences for magnetic-less PR-based converters have been enumerated and downselected in [5] based on high-efficiency behaviors and practical characteristics. One of the highest-efficiency step-down switching sequences in this set is the V_{in} - V_{out} , Zero, V_{out} sequence, named for the consecutive voltages v_p of its energy transfer stages. This six-stage switching sequence can be realized with the topology of Fig. 1 and the waveforms of Fig. 2.

This switching sequence maintains high-efficiency behaviors such as soft charging of the PR's capacitance C_p , zerovoltage switching (ZVS), all-positive instantaneous power transfer, and minimal charge circulation across wide operating ranges. This switching sequence likewise maintains constant theoretical efficiency for a given V_{in} and P_{out} in the $\frac{1}{2} < \frac{V_{out}}{V_{in}} < 1$ voltage conversion range, allowing for highefficiency regulation of V_{out} . The PR's amplitude of resonance (i.e., the amplitude I_L of its assumed-sinusoidal i_L in Fig. 1) for this sequence and operating region can be modeled as [5]:

$$I_L = \pi \left(\frac{P_{out}}{V_{in}} + fC_p V_{in} \right) \tag{1}$$

for which P_{out} is the power delivered to the load, f is the switching frequency, and V_{in} and C_p are as defined in Fig. 1.

We adopt the V_{in} - V_{out} , Zero, V_{out} switching sequence and its corresponding topology in Fig. 1 for this prototype; more analysis of its operation can be found in [5].

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Fig. 1. Topology corresponding to the V_{in} - V_{out} , Zero, V_{out} switching sequence proposed in [5]. The PR is represented with the Butterworth-Van Dyke model for operation near its fundamental resonance [12].



Fig. 2. Simulated waveforms for switching sequence V_{in} - V_{out} , Zero, V_{out} with PR parameters in Table II. V_{in} = 275 V, V_{out} = 150 V, P_{out} = 12 W.

B. Piezoelectric Resonator

The performance of a PR can vary widely based on its material, vibration mode, geometric dimensions, electrode pattern, mechanical mounting structure, and electrical contacts. A typical first step in the PR design process is co-selection of a material and intended vibration mode. Figures of merit (FOMs) for piezoelectric materials and vibration modes have been derived in [11] based on the highest-efficiency switching sequence detailed in Section II-A. One promising material and mode combination for high volumetric power density is the PZT radial mode, which has an extremely high FOM for volumetric energy handling density (i.e., power density normalized to frequency) and an acceptably high FOM for mechanical efficiency. The radial vibration mode is visualized in Fig. 3, and its mechanical efficiency FOM (FOM_M) is

$$\text{FOM}_M = \left(\frac{P_{out}}{P_{loss}}\right)_{max} = \frac{1}{2\pi^2 B_o R_o} \tag{2}$$

where $B_o = \varepsilon_{33}^T (1 - k_p^2) \frac{\kappa_o v_a}{4\pi}$ and $R_o = \frac{\kappa_{o,r}^2 - (1 - \sigma^2)}{Q_m k_p^2 \varepsilon_{33}^T v_a \kappa_{o,r} (1 + \sigma)}$ for which material properties are defined in Table I.

Besides its FOMs, the radial vibration mode is also advantageous in that (a) it is the lowest-frequency mode for a circular



Fig. 3. Example illustration of the radial vibration mode with electrodes denoted by shaded areas, displacement directions marked with red arrows, and the material's polarization direction shown with 'P'. Circuit model parameters are provided in terms of material properties defined in Table I [13].

TABLE I PIEZOELECTRIC MATERIAL PROPERTIES AND TYPICAL PZT VALUES

Symbol	Name	APC 841 Value*		
Q_m	Mechanical Quality Factor	1400		
k_p	Electromechanical Coupling Factor	0.6		
ε_{33}^T	Permittivity at Constant Stress	12.2 nF/m		
v_a	Acoustic Velocity	3.07 km/s		
σ	Poisson's Ratio	0.395		
$\kappa_{o,r}$	Normalized Wave Number at f_r	2.11		
$ar{\kappa}_o$	Normalized Wave Number at Maximum Efficiency	2.28		

 $^{*}Q_{m}$, k_{p} , and ε_{33}^{T} are provided by [14]. Others are calculated as in [11], [13].

disc, which minimizes the presence of spurious modes¹ in the PR's inductive frequency region, and (b) its necessary shape for maximum efficiency is more planar than that of other modes², providing more surface area for heat extraction. Discrete radial-mode PZT components are also widely available and have been demonstrated with high efficiency in multiple power converter designs to date [5], [8], [9], [11]. We therefore adopt the PZT radial mode for this prototype; more analysis of its characteristics can be found in [11].

The FOMs proposed in [11] correspond to PR geometry design conditions for achieving both maximum efficiency and maximum energy handling density at a desired converter operating point. These geometry conditions may also be applied to find the converter operating points that maximally utilize a given PR. For a PR operating in the radial mode, the V_{in} and P_{out} corresponding to maximum efficiency and loss-limited volumetric energy handling density are:

$$V_{in} = \sqrt{\frac{al \cdot H \cdot \text{FOM}_M}{B_o}} \tag{3}$$

$$P_{out} = \pi a^2 \cdot H \cdot \text{FOM}_M \tag{4}$$

where *H* is the PR's areal loss density (i.e., $\frac{P_{loss}}{\pi a^2}$) and describes the PR's thermal management requirement assuming most heat extraction occurs through its electrode surface(s). Thus, maximum loss-limited energy handling density is set by the maximum *H* that a PR's thermal design can accommodate. For lower values of *H*, maximum efficiency can still be

¹Spurious modes (i.e., minor resonant modes that increase loss) are often higher-order harmonics of a component's lower-frequency vibration modes.

²The radial vibration mode is one of several "perpendicular" vibration modes as defined in [11], which tend to require more planar shapes than "parallel" vibration modes for maximum efficiency.



Fig. 4. Experimental prototype based on the topology of Fig. 1 with an APC International PR (part 186: APC 841 material, 2a = 4.75 mm, 2l = 0.67 mm) mounted with a Keystone Electronics coin battery holder (part 500). All switches are EPC2012C GaN FETs, located under the PR mount on the board. Gate circuitry includes Texas Instruments UCC27611 gate drivers and ISO7420MD digital isolators.

achieved for any V_{in} and P_{out} that satisfy (3)-(4). We note that these relationships for other vibration modes, stress-limited density, or electric-field-limited density can also be derived from the framework of [11].

While these analyses assume ideal switching devices, the presence of significant switch capacitance can be detrimental to a PR's efficiency and power density capability. Switch capacitance also requires resonance between energy transfer stages for ZVS, necessitating more PR charge displacement for the same P_{out} . Switch capacitance may be integrated into (2)-(4) above by substituting B_o for B_{o+sw} , where

$$B_{o+sw} = \left(1 + \frac{2C_{oss}}{C_p}\right)B_o\tag{5}$$

and C_{oss} equals the effective switch capacitance. Thus, the impact of switch capacitance on achievable efficiency and power density is minimized as $\frac{2C_{oss}}{C_p} \rightarrow 0$.

III. CONVERTER PROTOTYPE

As a case study, we confine this prototype to off-theshelf piezoelectric components and evaluate candidates according to their power densities at their maximum-utilization operating points in (3) and (4). This calculation assumes H = 1 W/cm² and considers suitable switch capacitance, requiring co-selection of a switching device capable of supporting the suggested V_{in} in (3) with minimal capacitance compared to C_p . We select the APC International part 186 (APC 841 disc³, 2a = 4.75 mm, 2l = 0.67 mm) with EPC2012C FETs for this prototype; the analysis of Section II-B suggests this combination to be capable of 1 kW/cm³ PR power handling density at $V_{in} = 275$ V and $P_{out} \approx 12$ W.

As pictured in Fig. 4, we implement this design on a twolayer 1-oz copper printed circuit board with the parts listed in Fig. 4's caption. For this size PR, traditional mounting structures present considerable trade-offs: solder joints provide a reliable electrical connection but degrade Q_m if too large and break if too small, and spring mounts provide high



Fig. 5. Experimental waveforms at $V_{in} = 275$ V, $V_{out} = 150$ V, $P_{out} = 12$ W, and f = 493 kHz with the prototype pictured in Fig. 4.

TABLE II Characterized Prototype Model Parameters									
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C_{p+par}	L	C	R	Q_m	k_p	$\kappa_{o,r}$	$\bar{\kappa}_o$
457 pF	1.51 mH	75.2 pF	4.45 Ω	1030	0.424	2.05	2.13

 Q_m but scratch the electrode if too tight and lose electrical connection if too loose. For demonstration purposes, the PR in this prototype is mounted with a modified coin battery holder (Keystone Electronics part 500), which provides a reliable electrical connection with a wide contact point and an acceptable degradation of Q_m . We note that this structure permits lateral PR movement, and the PR settles to the position shown in Fig. 4 upon initial converter operation.

For all experiments, we operate this converter with a constant-voltage load and forced convection of 300 LFM using a server fan (Nidec part M33406-55G10). We control the converter with open-loop switching times, which we manually tune at each operating point for the switching sequence's high-efficiency behaviors discussed in Section II-A. Control handles for tuning include frequency, duty cycle of each half-bridge, phase shift between half-bridges, and dead time, and there is one unique tuning point at which all of the sequence's high-efficiency behaviors are achieved for a given V_{in} , V_{out} , and P_{out} . The result is the experimental waveforms shown in Fig. 5, which compare closely in form with those in Fig. 2.

IV. EXPERIMENTAL RESULTS

To contextualize this prototype's performance, we conduct a small-signal characterization of the PR mounted in this fullyassembled prototype using an impedance analyzer with no bias voltage. A frequency sweep throughout the PR's inductive region is shown in Fig. 6a, revealing near-ideal smoothness except for one discontinuity at 495 kHz. This discontinuity causes the equivalent series resistance and phase to locally increase and decrease, respectively. Fitting the Butterworth-Van Dyke equivalent circuit to this impedance curve yields the parameters shown in Table II, though we note that C_{p+par} is an overestimate since switch capacitance decreases with respect to bias voltage. The PR's Q_m , k_p , $\kappa_{o,r}$, and $\bar{\kappa}_o$ are characterized as described in [11], [13] and translate to an expected maximum PR efficiency of 98.2% at 491 kHz.

We test this converter's power stage efficiency vs. P_{out} for three different input/output voltage levels, each with the same conversion ratio, and Fig. 6b displays the results. This converter achieves competitive efficiency across a wide operating range and a full load efficiency of 93.3%. The maximum

³Although other materials considered in [11] have higher theoretical FOM_M, we select APC 841 for its high experimental efficiency demonstrated in [11] and its wide availability in off-the-shelf parts.



Fig. 6. (a) Small-signal impedance characteristic of the PR in the fully-assembled prototype pictured in Fig. 4, obtained after experiments to capture the PR's steady-state position in the mounting structure. Corresponding circuit model parameters are provided in Table II. (b) Experimental power-stage efficiency vs. P_{out} for various V_{in} (marked) each with $V_{out} = \frac{6}{11}V_{in}$; same data as Fig. 6c. (c) Experimental power-stage efficiency vs. f for various V_{in} (marked) each with $V_{out} = \frac{6}{11}V_{in}$; same data as Fig. 6b. Efficiencies do not consider auxiliary power.

observed efficiency for the lowest voltage level ($V_{in} = 55$ V) approaches the theoretical maximum PR efficiency of 98.2%. However, maximum efficiency is observed to be lower for higher voltage levels, which correspond to greater I_L . This dependence on excitation level is a departure from the framework described in Section II, in which maximum efficiency is a function of only Q_m and material properties. This suggests the piezoelectric component's material properties and/or loss characteristics to be nonlinear with respect to excitation level.

Fig. 6c plots these efficiency curves with respect to frequency, further highlighting the aforementioned discrepancies between voltage levels. The downward efficiency spikes between 491 kHz and 495 kHz may be attributed to the impedance discontinuity shown in Fig. 6a. The $V_{in} = 55$ V efficiency characteristic rebounds from this spike at lower frequencies, suggesting that the $V_{in} = 165$ V and $V_{in} = 275$ V efficiencies may do the same if operated at lower frequency (and therefore higher power).

Previous reports for PR power handling density in [6], [9], [10] have considered only the component's "active" volume between its electrodes, in which most energy is assumed to be stored. This does not consider the component's mounting structure (including "inactive" material used for anchoring) or electrical connections, as these aspects of PR design are yet to be optimized for power conversion. Adopting this standard, this prototype achieves a piezoelectric component power handling density of 1.01 kW/cm³. We validate the stability of this operating point with ten minutes of continuous operation, during which the prototype maintains the same waveforms without need to adjust its open-loop switching times. After this ten-minute period, the PR is thermally stable at <36 °C with forced convection of 300 LFM.

V. CONCLUSION

The observed piezoelectric component power handling density of 1.01 kW/cm³ represents a substantial increase over other recent piezoelectric-based dc-dc converter prototypes, which report 148 W/cm³ [6], 176.8 W/cm³ [9], and 128 W/cm³ [10]. All four prototypes are based on the same family of high-efficiency switching sequences, so the density increase may be attributed to this prototype's high-energy-handlingdensity PR design according to the FOMs and geometry conditions in [11]. This marks a significant milestone in demonstrating the power density capabilities of piezoelectrics and their miniaturization potential for power conversion.

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